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硬件配置:

- 1. Beckhoff 控制器 CX5010-0112 winCE 系统;
- 2. 以 ModScan32 模拟触摸屏发送和接收数据。
- 3. TC2 软件(注意 TC2 与 TC3 操作有很大区别)

准备:

- 1. 安装 TwinCAT_Modbus_Server_CE 插件。
- 2. 安装完成后,在路径: C:\TwinCAT\CE\TCModbusTCP\Install 下复制 TcModbusTcpSvrCe.I586 到倍福控制器的 CF 卡中。
- 3. 将控制器连接显示屏或者远程接管控制器(CERhost),双击 TcModbusTcpSvrCe.I586 文件,自动安装。
- 4. 在 TC2 PLC 中定义如下变量:

mb0_10 AT %MB0 :ARRAY[1..1000] OF WORD; lb0_10 AT %IB0 :ARRAY[1..1000] OF WORD; Qb0_10 AT %QB0 :ARRAY[1..1000] OF WORD; mb_Input_Coils : ARRAY [0..255] OF BOOL; mb_Output_Coils : ARRAY [0..255] OF BOOL; mb_Input_Registers : ARRAY [0..255] OF WORD; mb_Output_Registers : ARRAY [0..255] OF WORD; mb_Output_Registers : ARRAY [0..255] OF WORD; mb_M颜色变量分别代表不同的地址,但都可以实现 Modbus TCP 通信。 编译,下载,运行。

5 打开 ModScan32 软件,设定 IP 地址为控制器的 IP 地址,连接成功后监测。

数据测试:

Mapping between Modbus and ADS

In Modbus, the following four addressing areas are defined:

Modbus areas	Data type	Access
Digital inputs (discrete inputs)	1 bit	read only
Digital outputs (coils)	1 bit	read and write
Input register	16 bit	read only
Output register	16 bit	read and write

The individual areas can be addressed with 0 - 0xFFFF. The 🔼 server maps these addresses to the individual ADS areas. The standard settings are shown in the following ta

Modbus areas	Modbus address	ADS area	
Digital inputs	0x0000 - 0x7FFF	Index group	Index offset
		0xF021 - process image of the physical inputs (bit access)	0x0
	0x8000 - 0x80FF	Name of the variables in the PLC program	Data type
		.mb_Input_Coils	ARRAY [0255] OF BOOL
Digital outputs (coils)	0x0000 - 0x7FFF	Index group	Index offset
		0xF031 - process image of the physical outputs (bit access)	0x0
	0x8000 - 0x80FF	Name of the variables in the PLC program	Data type
		.mb_Output_Coils	ARRAY [0255] OF BOOL
Input registers	0x0000 - 0x7FFF	Index group	Index offset
		0xF020 - process image of the physical inputs	0x0
	0x8000 - 0x80FF	Name of the variables in the PLC program	Data type
		.mb_Input_Registers	ARRAY [0255] OF WORD
Output registers	0x0000 - 0x2FFF	Index group	Index offset
		0xF030 - process image of the physical outputs	0x0
	0x3000 - 0x5FFF	0x4020 - PLC memory area	0x0
	0x6000 - 0x7FFF	0x4040 - PLC data area	0x0
	0x8000 - 0x80FF	Name of the variables in the PLC program	Data type
		.mb_Output_Registers	ARRAY [0255] OF WORD

首先测试<u>自定义变量</u>的数据:

mb_Input_Coils	: ARRAY [0255] OF BOOL;
mb_Output_Coils	: ARRAY [0255] OF BOOL;
mb_Input_Registers	: ARRAY [0255] OF WORD;
mb_Output_Registers	: ARRAY [0255] OF WORD;

由上面表格可知,自定义变量的数据地址自动偏移 0x8000(32768)<u>+1</u> BooL 量输入(只读)

	_	File Connection Setup View Window Help
. ⊞Ib0_10 (%IB0)		
□ □ □ □ (%QB0)		
E-mb_Input_Coils	_	
mb_input_coi= TRUE		
mb_input_coi_ = FALSE		- ModSan?
mb Input Coi = FALSE		
mb_Input_Coi = FALSE		Device Id: 1
mb_Input_Coi = FALSE	\mathbf{N}	Address: 32769 MODBUS Point Type Number of F
mb_Input_Coi = FALSE		wobbost sink type valid Slave
mb_Input_Coi = FALSE		Length: 100 02: INPUT STATUS
mb_Input_Col = FALSE		
mb_input_Coi = EALSE		
mb_input_coi = FALSE		
mb Input Coi = FALSE		100000 (1) 100000 (0) 100000 (0) 100000 (0) 1000
mb_Input_Coi = FALSE		132770: <1> 132776: <0> 132783: <0> 132790: <0> 132790: <0> 132790: <0> 132790: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791: <0> 132791
i i mb Input Coi = FALSE		132771: <0> 132778: <0> 132785: <0> 132792: <0> 1327
BOOI)	
BOOL 重制山、陕/马	1	
⊞mb0_10 (%MB0) ▲		File Connection Setup View Window Help
	<u></u>	
⊞™QDU_TU (%QBU) ⊞™mb_Input_Coils	_	
E-mb_output_Coils		50 53 59 52 52 54 56 55 55 55 55 55
mb Output C = TRUE	• • •	
mb_Output_C = FALSE		- ModSca2
mb_Output_C = TRUE		
mb_Output_C = FALSE		Device Id: 1
mb_Output_C = ALSE		Address: 32769 MODBUS Point Type
mb_Output_C = FALSE	\mathbf{N}	
mb_Output_C = FALSE		
mb_output_C = FALSE		Write Loil
mb_Output C = FALSE		
mb_Output_C = FALSE		Node: 1
mb_Output_C = FALSE		032769 (1) 03 Address: 32772
mb_Output_C = FALSE		032770: 🔨 03 Value
mb_Output_C = FALSE		032771: <1> 03 C Off @ Dn
mb_Output_C = ALSE		$0.32773 \cdot \langle 0 \rangle = 0.3$
		032774: <0> 03 Update Cancel
mb_Output_C = FALSE		032775: <0> 03

实数输入 (只读)

⊟mb_Input_Regist mb_Input_Re = 37 mb_Input_Re = 0	 🖿 ModSca2				
mb_Input_Re = 0 mb_Input_Re = 46 mb_Input_Re = 0	Address: 32	769	Device Id: MODBUS Po	1 int Type	
mb_Input_Re = 0 mb_Input_Re = 0 mb_Input_Re = 0 mb_Input_Re = 0 mb_Input_Re = 0	Length: 10	0 04: 1	NPUT REGIS	STER	•
mb_Input_Re = 0 mb_Input_Re = 0 mb_Input_Re = 0 mb_Input_Re = 0	332769: <000 332770: <000 332771: <000 332772: <000	37> 332776: 00> 332777: 00> 332778: 46> 332779:	<00000> <00000> <00000> <00000>	332783: 332784: 332785: 332785: 332786:	< 000 < 000 < 000 < 000

实数输出(读/写)

⊡....

mb_Output_Regi mb_Output_R = 17 mb_Output_R = 0 	Address: 32769 Length: 100	Device Id: 1 MODBUS Point Type
mb_Output_R = 0 mb_Output_R = 0	432769: <00017>	Write Register 🛛 🔀 🕫
mb_Output_R = 0 mb_Output_R = 0 mb_Output_R = 0	432770: <00069> 432771: <00000> 432772: <00022> 432773: <00000>	00 Node: 1 00
mb_Output_R = 0 mb_Output_R = 0	432774: <00000> 432775: <00000>	Address: 32770 00
mb_Output_R = 0 mb_Output_R = 0	<u> </u>	Value: 69
mb_Output_R = 0 mb_Output_R = 0 mb_Output_R = 0		[[[]] Cancel

再测试定义变量地址:

Ib0_10 AT %IB0 :ARRAY[1..9] OF BOOL;

Ib0_11 AT %IB10 :ARRAY[1..100] OF WORD;

Qb0_10 AT %QB0 :ARRAY[1..9] OF BOOL;

Qb0_11 AT %QB10 :ARRAY[1..100] OF WORD;

请注意倍福 PLC 中是用 1 个 Byte 来处理 bool 变量的。SO:

BooL 量输入(只读):



BOOL 量输出(读/写):	
lb0_10[1] = <mark>TRUE</mark> lb0_10[2] = TRUE	
lb0_10[3] = FALSE lb0_10[4] = FALSE	🖿 ModSca3
	Address: 0001 Device Id: 1 Nu MODBUS Point Type Va
	Length: 100 01: COIL STATUS
⊞lb0_11 (%lB10) ⊟Qb0_10 (%QB0)	
Qb0_10[1] = TRUE	00001:►1> 00010: <0> Write Coil
Qb0_10[2] = TRUE	00002: <0> 00011: <0> 00003: <0> 00012: <0> Node: 1
$Qb0_10[4] = FALSE$	000005: (0) 00013: (0) 000005: (0) 00014: (0) Address: 17 000006: (0) 00015: (0)
ubu_1u[b] = FALSE Qb0_10[7] = FALSE Qb0_10[8] = FALSE	00007: <0> 00016: <0> 00008 <0> 00017: <1> 00009: 1> 00018: <0> 00009: 1> 00018: <0>
^l Qb0_10[9] = <mark>FALSE</mark> ⊡Qb0_11 (%QB10)	Cancel



⊡lb0_10 (%lB0)		
lb0_10[1] = <u>TRUE</u>	01 10 0x 32 12 64 64	
Ib0_10[2] = <u>TRUE</u>		
Ib0_10[3] = <mark>FALSE</mark>	- VodSea3	
Ib0_10[4] = <u>FALSE</u>	I modbeab	
Ib0_10[5] = <u>FALSE</u>	Device Id: 1	
Ib0_10[6] = <u>FALSE</u>	Address: 0001	nup
Ib0_10[7] = <u>FALSE</u>	MUDBUS Point Type Va	ilid {
Ib0_10[8] = <u>FALSE</u>	Length: 100 04: INPUT REGISTER 🔻	
[:] lb0_10[9] = FALSE		
⊡lb0_11 (%lB10)		
lb0_11[1] = 37		
lb0_11[2] = 0	30001 · 2002575 30010 · 2000005 30019 · 2000005 1	2002
lb0_11[3] = 0	30002: <00000> 30011: <00000> 30020: <00000> 3	3002
lb0_11[4] = 0	3000 3: <00000> 30012: <00000> 30021: <00000> 3	3003
lb0_11[5] = 0	30004: <00000> 30013: <00000> 30022: <00000> 3	3003
lb0_11[6] = 0	30005: <80000> 30014: <00000> 30023: <00000> 3 30006: <00037> 30015: <00000> 30024: <00000> 3	2003
i1b0 11171 = 0		1003

注意: 30001-30005 倍前面定义的 Bool 输入空间占用。

实数输入(读/写)

Ib0_10[6] = FALSE Ib0_10[7] = FALSE Ib0_10[8] = FALSE Ib0_10[9] = FALSE Ib0_11 (%IB10) Ib0_10 (%QB0)	Address: 0001 Device Id: 1 MODBUS Point Type Length: 100 03: HOLDING REGISTER
□Qb0_11 (%QB10) Qb0_11[1] = 35	40001: <00257> 4 Write Register
Qb0_11[2] = 29 Qb0_11[3] = 0 Qb0_11[4] = 0 Qb0_11[5] = 0 Qb0_11[6] = 0 Qb0_11[6] = 0 Qb0_11[8] = 0 Qb0_11[9] = 0 Qb0_11[10] = 0 Qb0_11[11] = 0	40002: <00001> 4(40003: <00000> 4(40004: <00000> 4(40005: <00000> 4(40006: <00035> 4(40007: <00029> 4(40008: <00000> 4(40009: <00000> 4(40009: <00000> 4(Value: 29